
svkcore Documentation

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GET START

1.1 install

1.1.1 pip

```
1 pip install svkcore
```

1.1.2 from source

```
1 git clone https://github.com/ZhaoJianghua/simple-vision-kit.git
2 cd simple-vision-kit
3 python setup.py install
```

1.2 usage

1.2.1 common

- io: load and save data more convenient

```
1 from svkcore import common
2
3 # save & load json
4 data = {'data': 1, "message": "hello"}
5 common.save_json(data, 'user_data.json')
6 data = common.load_json('user_data.json')
7
8 # save & load pickle
9 data = {'data': np.array([1]), "message": "hello"}
10 common.save_pickle(data, 'user_data.pkl')
11 data = common.load_pickle(data, 'user_data.pkl')
12
13 # read & write image platform compatile with win system
14 img = common.cv2imread("path")
15 common.cv2imwrite("path", img)
```

- collect data: collect from a directory

```
1 from svkcore import common
2
3 # collect images/annotations
4 img_ps = common.find_file_recursive(directory="root", suffixes=[".jpg"], ignore_
   ↳ case=True)
5 print(img_ps[:1])
6 # get basename head
7 hd = common.bsn_head("root/xxx/xxxx.jpg")
8 print(hd)
9 # collect examples
10 examples = common.collect_examples(directory="dir", suffixes_list=[[".jpg"], [".xml"]])
11 print(examples[:1])
12 # or use collect_pascal_data to collect pascal format data
13 examples = common.collect_pascal_data(directory="dir")
14 print(examples[:1])
```

- numpy operations: some useful numpy operations

```
1 indexes = common.ndarray_index(shape=[7, 8])
2 distances = common.points_distance(points0=[[0, 0]], points1=[[1, 1]])
3 grids = common.generate_grid(panel_size=[1024, 1024], grid_size=(256, 256),
4                               overlap_size=(24, 24))
5 # common.seg2point(seg, max_diameter: int, min_distance, fb_threshold: float = 0.5,
6 #                  min_fore_count: int = 1, max_fore_count: int = -1,
7 #                  avg_fore_score: float = 0.55, distance_weights=(1., 1.))
8 # common.seg2line(seg, fb_threshold=0.5, smooth_width=3, partition_width=20,
9 #                 partition_height=30)
```

1.2.2 annotation

Pascal and coco annotation load, save and convert.

```
1 from svkcore import annotation
2
3 # load pascal annotation
4 ann = annotation.DTAnnotation.load("pascal_annotation_file")
5 for obj in ann:
6     print(obj.name)
7     print(obj.bndbox)
8     print(obj.difficult)
9     obj.name = obj.name + "-new"
10 ann.dump("pascal_annotation_file_new")
11
12 # convert pascal data to coco format
13 dataset = annotation.DTDataset.load_pascal(annotation_paths=[],
14                                             image_paths=[])
15 dataset.dump_coco("coco_format_dataset_file")
```

1.2.3 shapes

Base shapes which usually be used in image tasks.

```

1 from svkcore import shapes
2
3 # shapes and operations
4 point0 = shapes.Point([0, 0])
5 point1 = shapes.Point([1, 1])
6 points = shapes.Points([point0, point1])
7 bndbox0 = points.bounding_box()
8 bndbox1 = shapes.Box([0, 0, 1, 1])
9 bsize = bndbox1.bsize()
10 center = bndbox1.center()
11 polygon = bndbox1.to_polygon()
12 mask = bndbox1.to_mask()
13 bndbox2 = polygon.bounding_box()
14 area = polygon.area()

```

1.2.4 visualize

Visualize part for visualize common shapes.

```

1 from PIL import Image
2 from svkcore import visualize
3 from svkcore import annotation
4
5 pil_image = Image.new("RGB", [600, 600])
6 boxes = [[100, 200, 400, 300]]
7 visualize.draw_boxes(pil_image, boxes=boxes)
8 visualize.draw_texts(pil_image, xys=[(100, 200)], texts=["box"])
9 visualize.draw_points(pil_image, points=[[50, 50]])
10 visualize.draw_lines(pil_image, lines=[[0, 0], [300, 300]])
11
12 ann = annotation.DTAnnotation.load("path")
13 visualize.draw_annotation(pil_image, ann, name2cls={},
14                           add_unknown_name=True)

```


SVKCORE PACKAGE

2.1 svkcore.annotation

2.1.1 svkcore.annotation.pascal

```
class svkcore.annotation.pascal.DTAnnotation(filename: str, size, objects: List[DTObject],  
                                             segmented=False, **kwargs)
```

Bases: *object*

Detection Annotation: An annotation for object detection

dump(*path*)

Dump DTAnnotation to a file

Parameters

path (*str*) – dumped file path

dumpd()

Dump DTAnnotation to a dict

Returns

a dict contains DTAnnotation information

Return type

dict

static load(*path*: *str*)

Load DTAnnotation from a file

Parameters

path – file path

Returns

loaded DTAnnotation object

Return type

DTAnnotation

static loadd(*obj*: *dict*)

Load DTAnnotation from a dict

Parameters

obj – a dict contains DTAnnotation information

Returns

loaded DTAnnotation object

Return type*DTAnnotation***size_keys** = ('width', 'height', 'depth')**class** svkcore.annotation.pascal.DTDataset(*annotations, images, categories*)Bases: *object*

Detection dataset: A collection of annotations for object detection

dump_coco(*path*)

Save dataset to coco format

Parameters**path** – coco format annotation path**Returns**

None

dump_pascal(*annotation_dir*)

Save dataset to pascal format

Parameters**annotation_dir** – pascal format annotations directory**Returns**

None

dump_yolo(*dataset_dir*)

Save dataset to yolo format

Parameters**dataset_dir** – yolo format dataset directory**Returns**

None

static load_coco(*annotation_path, image_root*)

Load coco format dataset

Parameters

- **annotation_path** – json format annotation file path
- **image_root** – image root directory

Returns

DTDataset object

static load_pascal(*annotation_paths, image_paths*)

Load pascal format dataset

Parameters

- **annotation_paths** – a list of pascal format annotation file path
- **image_paths** – a list of image path respect with each annotation file

Returns

DTDataset object

```
class svkcore.annotation.pascal.DTObject(name, bndbox=None, polygon=None, mask=None,  
                                         pose='Unspecified', truncated=False, difficult=False)
```

Bases: `object`

Detection object: base object for object detection

```
box_keys = ('xmin', 'ymin', 'xmax', 'ymax')
```

```
dumpd() → dict
```

Dump DTObject to a dict

Returns

a dict contains DTObject information

Return type

`dict`

```
static loadd(obj: dict)
```

Load DTObject from a dict

Parameters

obj – a dict contains DTObject information

Returns

loaded DTObject object

Return type

`DTObject`

```
svkcore.annotation.pascal.read_annotation(annotation_path)
```

Read object detection annotation of xml format file

Parameters

annotation_path (`str`) – file path of annotation

Returns

a dict of detection annotation

Return type

`dict`

```
svkcore.annotation.pascal.write_annotation(annotation_path, annotation)
```

Write object detection annotation to a xml format file

Parameters

- **annotation_path** – file path of annotation
- **annotation** – a dict of detection annotation

2.2 svkcore.common

2.2.1 svkcore.common.common

This module provides common utility functions for simple vision kit. It includes functions for computing md5 hash, aligning file paths, grouping lists, finding files recursively, collecting examples, and encoding/decoding images using base64.

`svkcore.common.common.align_paths(paths0, paths1, *args, sort=False, key_fn=None)`

Align paths base on its name head This function will delete dis-matched paths with no prompt.

Parameters

- **paths0** (*list*) – the first list of file paths
- **paths1** (*list*) – the second list of file paths
- **args** – the others list of file paths
- **sort** (*bool*) – sorted output by key
- **key_fn** (*callable*) – extract align key function, default is `basename_head()`

Returns

align paths in list

Return type

list

`svkcore.common.common.b64decode_image(data: bytes) → Image`

Decode bytes data of encoded image to an instance of PIL.Image.Image

Parameters

data (*bytes*) – base64 encoded bytes image data

Returns

An instance of Image.Image represents the decode image

Return type

PIL.Image.Image

`svkcore.common.common.b64encode_image(image: Image, format: str = 'JPEG') → bytes`

Convert PIL.Image.Image object to bytes data use base64 encode

Parameters

- **image** (*PIL . Image . Image*) – an instance of PIL.Image.Image
- **format** (*str*) – a string represents image encoding format. could be “JPEG” or “PNG”

Returns

base64 encoded image data

Return type

bytes

`svkcore.common.common.basename_head(path, sep='.', align_left=False)`

Get basename head of a path

Parameters

- **path** (*str*) – a path
- **sep** (*str*) – a separator str to split path’s basename. Default is ".".
- **align_left** (*bool*) – split basename with separator from left or not. Default is False. And this function will split basename from right.

Returns

the head part of basename of path

Return type

str

`svkcore.common.common.bsn_head(path, sep='.', align_left=False)`

Get basename head of a path

Parameters

- **path** (*str*) – a path
- **sep** (*str*) – a separator str to split path's basename. Default is ".".
- **align_left** (*bool*) – split basename with separator from left or not. Default is False. And this function will split basename from right.

Returns

the head part of basename of path

Return type

str

`svkcore.common.common.collect_examples(directory, suffixes_list, ignore_case=False, sort=False, key_fn=None)`

Collect examples from one directory base on given suffixes list

Parameters

- **directory** (*str*) – Root directory of examples
- **suffixes_list** (*list*) – A list of suffix list for example's each part
- **ignore_case** (*bool*) – ignore case when match file name suffix. Default is False.
- **sort** (*bool*) – sort the result list by key. Default is False.
- **key_fn** (*callable*) – a function use to extract align key, default is `basename_head()`

Returns

all matched file paths list

Return type

list

`svkcore.common.common.collect_pascal_data(directory)`

Collect pascal format dataset

Parameters

directory (*str*) – the root directory of a pascal dataset

Returns

two list of images and annotations of the the pascal dataset

Return type

list

`svkcore.common.common.find_file_recursive(directory, suffixes, ignore_case=False)`

Find all files with provided suffixes

Parameters

- **directory** (*str*) – the target directory
- **suffixes** (*Union[str, list]*) – a suffix or a list of suffixes of file to be find
- **ignore_case** (*bool*) – match file suffix in case ignore mode

Returns

a list which returns the path to the file which meets the postfix

Return type`list``svkcore.common.common.find_files(directory, suffixes, ignore_case=False)`

Find all files with provided suffixes

Parameters

- **directory** (`str`) – the target directory
- **suffixes** (`Union[str, list]`) – a suffix or a list of suffixes of file to be find
- **ignore_case** (`bool`) – match file suffix in case ignore mode

Returns

a list which returns the path to the file which meets the postfix

Return type`list``svkcore.common.common.get_default_font(size: int = 24) → ImageFont`

Get a default PIL.ImageFont.ImageFont instance for show label name on image which could deal with both English and Chinese

Parameters

size (`int`) – font size

Returns

a font object

Return type`PIL.ImageFont.ImageFont``svkcore.common.common.group(lst, key, value=None) → Dict[object, list]`

Group list by key and return a dict. Each value of the result dict is a list. And each list contains all values with same key.

Parameters

- **lst** (`list`) – a list of objects to be group
- **key** (`Union[list, callable]`) – a list of key objects or a callable function map each item in lst to its key
- **value** (`Union[list, callable]`) – a list of value objects or a callable function map each item in lst to its value. Default is `None` and group will use `lst` as `value`.

Returns

grouped result

Return type`Dict[object, list]``svkcore.common.common.group_map(_group: dict, func: Callable, with_key: bool = False)`

Do map on a group result

Parameters

- **_group** (`Dict[object, list]`) – a result dict of group
- **func** (`Callable`) – a function used to process value or key and value
- **with_key** (`bool`) – func process with key and value or only value. Default is `False`, only process value.

Returns

map result dict

Return type

dict

svkcore.common.common.**ifind_file_recursive**(*directory*, *suffixes*, *ignore_case=False*)

Find all files with provided suffixes

Parameters

- **directory** (*str*) – the target directory
- **suffixes** (*Union[str, list]*) – a suffix or a list of suffixes of file to be find
- **ignore_case** (*bool*) – match file suffix in case ignore mode

Returns

a generator which returns the path to the file which meets the postfix

Return type

a generator

svkcore.common.common.**image_md5**(*image: Image*) → *str*

Compute a image md5 value

Parameters**image** (*PIL.Image.Image*) – pillow image object to be hashed by md5**Returns**

md5 hash string

Return type*str*svkcore.common.common.**str_md5**(*_bytes: bytes*) → *str*

Compute string md5 value

Parameters**_bytes** (*bytes*) – data in bytes format to be hashed by md5**Returns**

md5 hash string

Return type*str*

2.2.2 svkcore.common.fileio

This module provides functions for file input/output operations, including copying files, loading and saving json, pickle, csv files, and reading and writing images using OpenCV.

svkcore.common.fileio.**copy_files**(*paths*, *dst_dir*, *src_dir=None*)Copy files in list paths from *src_dir* to *dst_dir***Parameters**

- **paths** (*list*) – a list of paths
- **dst_dir** (*str*) – destination directory
- **src_dir** (*str*) – root directory of all paths

`svkcore.common.fileio.cv2imread(path)`

Read image from file path using OpenCV

Parameters

path (*str*) – image file path

Returns

loaded image as numpy array

Return type

`numpy.ndarray`

`svkcore.common.fileio.cv2imwrite(path, img)`

This function is a compatible version of `cv2.imwrite`. It writes an image to the specified file path in .jpg format.

Parameters

- **path** (*str*) – output image file path
- **img** (`numpy.ndarray`) – output image data

`svkcore.common.fileio.load_csv(path, *, with_header=True, encoding=None)`

This function is used to load csv format file. It reads the csv file from the given path and returns the rows as a list of lists. If `with_header` is True, the first row is considered as the header and returned separately. If encoding is provided, it is used to decode the csv file.

Parameters

- **path** (*str*) – csv file path
- **with_header** (*bool*) – return result with data header
- **encoding** (*str*) – csv file encoding like `utf-8`, etc.

Returns

Return type

`list`

`svkcore.common.fileio.load_json(path, *, encoding=None, **kwargs)`

Load json format file

Parameters

- **path** (*str*) – json file path
- **encoding** (*str*) – json file encoding like `utf-8`, etc.
- **kwargs** – other options for `json.load`

Returns

loaded json object

Type

`object`

`svkcore.common.fileio.load_pickle(path)`

Load object from pickle format

Parameters

path (*str*) – pickle file path

Returns

loaded object

Return type

object

`svkcore.common.fileio.save_csv(rows, path, *, header=None, encoding=None)`

This function is used to save data into csv format file. If header is provided, header will place at the first row of the output csv file. If encoding is provided, it is used to decode the csv file.

Parameters

- **rows** (*list*) – a list of data row
- **path** (*str*) – csv file path
- **header** (*list*) – data header
- **encoding** (*str*) – csv file encoding like utf-8, etc.

`svkcore.common.fileio.save_json(obj, path, indent=2, ensure_ascii=False, *args, **kwargs)`

Save object as json format

Parameters

- **obj** (*object*) – object to be saved as json format
- **path** (*str*) – json file path
- **indent** (*int*) – number of spaces for indentation
- **ensure_ascii** (*bool*) – whether to ensure ascii encoding
- **args** – other options for *json.dump*
- **kwargs** – other options for *json.dump*

`svkcore.common.fileio.save_pickle(obj, path)`

Save object as pickle format

Parameters

- **obj** (*object*) – object to be saved as pickle format
- **path** (*str*) – pickle file path

2.2.3 svkcore.common.np_ops

Some common numpy operations

`svkcore.common.np_ops.circle_kernel(diameter, dtype=<class 'numpy.int32'>)`

Create circle kernel

Parameters

- **diameter** (*int*) – diameter of the circle
- **dtype** (*numpy.dtype, optional*) – data type of the kernel

Returns

circle kernel

Return type

numpy.ndarray

`svkcore.common.np_ops.ellipse_kernel(ksize, dtype=<class 'numpy.int32'>)`

Create ellipse kernel

Parameters

- **ksize** (*tuple*) – kernel size, a tuple of (height, width)
- **dtype** (*numpy.dtype, optional*) – data type of kernel

Returns

ellipse kernel

Return type

numpy.ndarray

`svkcore.common.np_ops.generate_grid(panel_size, grid_size=None, grid_num=None, overlap_size=None, overlap_ratio=None, allow_cross_boundary=False)`

Generate grid for crop image patches

Parameters

- **panel_size** (*bool*) – a tuple of image size (height, width)
- **grid_size** – a tuple of grid size (grid_height, grid_width)
- **grid_num** – a tuple of grid num (grid_rows, grid_column)
- **overlap_size** – a tuple of overlap size
- **overlap_ratio** – a tuple of grid overlap ratio
- **allow_cross_boundary** – allow the last row or column position cross panel or not

Returns

grids [rows, columns, 4], each grid consists (ymin, xmin, ymax, xmax)

Return type

np.ndarray

`svkcore.common.np_ops.ndarray_index(shape)`

Create np.ndarray index

Parameters

shape (*Union[list, tuple]*) – index array shape

Returns

np.ndarray index

Return type

np.ndarray

`svkcore.common.np_ops.nms_mask(seg, ksize=3, dtype=None)`

Non-maximum suppression mask for segmentation

Parameters

- **seg** (*np.ndarray*) – segmentation result, probability map between [0.0, 1.0]
- **ksize** (*int*) – kernel size for max pooling
- **dtype** (*np.dtype*) – data type of output mask

Returns

non-maximum suppression mask

Return type

np.ndarray

svkcore.common.np_ops.**points_distance**(points0, points1, weights=(1.0, 1.0))

Calculate distances between two point array

Parameters

- **points0** (np.ndarray) – a numpy array of shape (n, 2) representing the first set of points
- **points1** (np.ndarray) – a numpy array of shape (m, 2) representing the second set of points
- **weights** (tuple) – a tuple of two floats representing the weights for the distance calculation along the vertical and horizontal axes

Returns

a numpy array of shape (n, m) representing the distances between each pair of points from points0 and points1

Return type

np.ndarray

svkcore.common.np_ops.**seg2line**(seg, fb_threshold=0.5, smooth_width=3, partition_width=20, partition_height=30)

Find all valid lines for segmentation

Parameters

- **seg** (np.ndarray) – point object segmentation result, probability map between [0.0, 1.0]
- **fb_threshold** (float) – foreground vs background threshold
- **smooth_width** (float) – bin width for line x-coordinate smooth
- **partition_width** (float) – line will split when x-coordinate interval greater than partition_width
- **partition_height** (float) – line will split when y-coordinate interval greater than partition_height

Returns

a list of lines

Return type

list

svkcore.common.np_ops.**seg2point**(seg, max_diameter: int, min_distance, fb_threshold: float = 0.5, min_fore_count: int = 1, max_fore_count: int = -1, avg_fore_score: float = 0.55, distance_weights=(1.0, 1.0))

Find all valid points from segmentation

Parameters

- **seg** (np.ndarray) – point object segmentation result, probability map between [0.0, 1.0]
- **max_diameter** (int) – max_radius for a point
- **min_distance** (float) – min distance between two point center
- **fb_threshold** (float) – foreground vs background threshold
- **min_fore_count** (int) – The minimum count of foreground pixel
- **max_fore_count** (int) – The maximum count of foreground pixel

- **avg_fore_score** (*float*) – The minimum average fore score of foreground
- **distance_weights** (*tuple*) – distance value's weights of vertical and horizontal

Returns

A list of point

Return type

np.ndarray

2.3 svkcore.shapes

2.3.1 svkcore.shapes.shapes

Common shapes for object detection

class svkcore.shapes.shapes.Box(*obj*, *dtype=None*)

Bases: *Shape*

Box of 2d. Record top_left and bottom_right corner position of box.

area()

Calculate box area

Returns

box area

Return type

np.float

bsize()

Size of box

Returns

box size in format np.array([width, height])

Return type

np.ndarray

center()

Center point of a box

Returns

center point

Return type

Point

classmethod from_cxywh(*cxywh*)

Create box from format [min-x, min-y, max-x, max-y]

Returns

converted box in format [min-x, min-y, max-x, max-y]

Return type

Box

scale(*scale*)

Scale box

Parameters

scale – scale factor

Returns

a scaled box

Return type

Box

to_cxywh()

Convert box format to [center-x, center-y, width, height]

Returns

converted box in format [center-x, center-y, width, height]

Return type

np.ndarray

to_mask(*size=None*)

Convert box to mask

Parameters

size –

Returns

to_polygon()

Convert box to polygon from top_left and across top_right, bot_right and end to bot_left

Returns

the converted polygon

Return type

Polygon

class svkcore.shapes.shapes.**Boxes**(*obj, dtype=None*)

Bases: *Shape*

Collection of Box

areas()

Calculate boxes areas

Returns

boxes areas

Return type

np.ndarray

bsize()

Sizes of boxes

Returns

boxes sizes in format np.array([[width, height], ...])

Return type

np.ndarray

center()

Center points of a boxes

Returns

center points

Return type

Points

classmethod from_cxywh(cxywh)

Create box from format [min-x, min-y, max-x, max-y]

Returns

converted box in format [min-x, min-y, max-x, max-y]

Return type

Boxes

scale(scale)

Scale boxes

Parameters

scale – scale factor

Returns

a scaled boxes

Return type

Boxes

to_cxywh()

Convert box format to [center-x, center-y, width, height]

Returns

converted boxes in format [center-x, center-y, width, height]

Return type

np.ndarray

class svkcore.shapes.shapes.Line(obj, dtype=None)

Bases: *Points*

Line of 2d

length()

Calculate the length of a continuous line

Returns

the line length

Return type

np.float

class svkcore.shapes.shapes.Mask(obj, dtype=None)

Bases: *Shape*

Mask of 2d

area()

Calculate mask area

Returns

mask area

Return type

np.float

bounding_box()

Get the minimum bounding box of this mask

Returns

then minimum bounding box of this mask

Return type

Box

swap()

Swap mask shape coordinate order from x-y to y-x

Returns

swapped this mask

Return type

Mask

class svkcore.shapes.shapes.**Point**(obj, dtype=None)

Bases: *Shape*

Point of 2d

class svkcore.shapes.shapes.**Points**(obj, dtype=None)

Bases: *Point*

Collection of Points

bounding_box()

Get the minimum bounding box a collection of points

Returns

bounding box

Return type

Box

class svkcore.shapes.shapes.**Polygon**(obj, dtype=None)

Bases: *Shape*

Polygon of 2d

area()

Calculate polygon area use mask area calculate

Returns

polygon area

Return type

np.float

bounding_box()

Get the minimum bounding box of this polygon

Returns

bounding box

Return type

Box

to_mask(*size=None*)

Convert polygon to mask

Parameters

size – the final mask size. Default is None means use the minimum size that can overlap this mask

Returns

converted mask from polygon

Return type

np.ndarray

class svkcore.shapes.shapes.**Shape**(*obj, dtype=None*)

Bases: `object`

Base class for object detection shapes. Wrap a numpy.array object and add specified operations for each type shape.

numpy()

Get numpy data

Returns

shape data

Return type

np.ndarray

order = 0

swap()

Swap this shape coordinate order from x-y to y-x

Returns

swapped this shape

Return type

Shape

2.4 svkcore.visualize

2.4.1 svkcore.visualize.visualize

`svkcore.visualize.visualize.cv2image2pil`(*cv2_image: ndarray*) → `Image`

Convert openCV format image to PIL.Image.Image

Parameters

cv2_image – openCV format image instance

Returns

converted Image.Image instance

`svkcore.visualize.visualize.draw_annotation`(*image, annotation, name2cls, color_table=None, add_unknown_name=False*)

Draw DTAnnotation to an image

Parameters

- **image** (*PIL.Image.Image*) – A PIL.Image.Image object

- **annotation** (`DTAnnotation`) – An instance of `DTAnnotation`
- **name2cls** (`dict`) – a dict of name to its class id number
- **color_table** (`list`) – each class colors
- **add_unknown_name** (`bool`) – whether add a new name to `name2cls`, default is `False`

Returns

drew image

Return type

`PIL.Image.Image`

`svkcore.visualize.visualize.draw_boxes(image, boxes, color='red', width=0, fullfill=False)`

Draw boxes on image

Parameters

- **image** – A `PIL.Image` object
- **boxes** – a list of boxes
- **color** – boxes color
- **width** – line width
- **fullfill** – full fill boxes or not

Returns

drew image

`svkcore.visualize.visualize.draw_boxes_texts(image, boxes, texts, width=1, color='red')`

Draw boxes and its text information on image

Parameters

- **image** – A `PIL.Image` object
- **boxes** – A list of box
- **texts** – A list of text
- **width** – Line width, determines thickness of box and font size of text
- **color** – Color of boxes and texts

Returns

drew image

`svkcore.visualize.visualize.draw_detection_result(image, boxes, classes, display_strings, color_nums=100, scale=-1.0)`

Draw detection result

Parameters

- **image** – A `PIL.Image` object
- **boxes** – A list of box
- **classes** – A list of detection class index
- **display_strings** – A list of display string
- **color_nums** – The max number of different colors
- **scale** – visualize box and text scale. Default -1.0 means auto adjust scale by input image

Returns

drew image

`svkcore.visualize.visualize.draw_lines(image, lines, color='red', width=0)`

Draw boxes on lines

Parameters

- **image** – A PIL.Image object
- **lines** – a list of lines
- **color** – lines color
- **width** – line width

Returns

drew image

`svkcore.visualize.visualize.draw_masks(image, masks, color='red', alpha=0.5)`

Draw masks on image

Parameters

- **image** – A PIL.Image object
- **masks** – a list of masks
- **color** – mask color
- **alpha** – transport alpha

Returns

drew image

`svkcore.visualize.visualize.draw_points(image, points, color='red', scale=3, shape='.')`

Draw boxes on points

Parameters

- **image** – A PIL.Image object
- **points** – a list of points
- **color** – points color
- **scale** – points scale
- **shape** – visualize shape, 't' for triangle else for circle

Returns

drew image

`svkcore.visualize.visualize.draw_polygons(image, polygons, color='red', width=0, fullfill=False)`

Draw polygons on image

Parameters

- **image** – A PIL.Image object
- **polygons** – a list of polygons
- **color** – mask color
- **width** – line width
- **fullfill** – full fill polygon or not

Returns

drew image

`svkcore.visualize.visualize.draw_texts(image, xys, texts, color='red', back_color=None, font_size=12, position='topleft', offset=(0, 0), margin=(0, 0, 0, 0))`

Draw texts on image

Parameters

- **image** – A PIL.Image object
- **xys** – A list of corner's coordinate where text align
- **texts** – A list of texts
- **color** – Text color
- **back_color** –
- **font_size** – Font size
- **position** – text align position, enum string like: topleft/topright/bottomleft/bottomright/manu
- **offset** – A tuple vector of offset for 'manu' position
- **margin** – A tuple (left, top, right, bottom) denotes the margins to back boarder

Returns

drew image

`svkcore.visualize.visualize.generate_colors(num)`

Generate colors for drawing bounding boxes

`svkcore.visualize.visualize.images_gallery(image_list: Tuple[Image] | List[Image], n_cols: int = 6, n_rows: int | None = None, cell_size: Tuple[int] | List[int] = (224, 224), pad: int = 16, align: int = 0, back_color: Tuple[int] | List[int] | str = 'black', same_scale: bool = False) → Image`

Paste a list of images into one panel for better visualize

Parameters

- **image_list** – A list of Image.Image instance.
- **n_cols** – Max number of images to show in each row. If the number of image_list is less than n_cols, n_cols will be set as the number of image_list. Default value is 6.
- **n_rows** – Number of rows to show images. If n_cols is set, n_rows will be automatically calculated by

$$\text{ceil}(\frac{N}{n_cols})$$

Otherwise n_cols will be automatically calculated. Default value is None.

- **cell_size** – The size of cell where each image is placed in.
- **pad** – The pad width/height between two cells.
- **align** – The align mode. Set 0(center), 1(left/up), 2(right/bottom) to choose align mode in each cell.
- **back_color** – Background color.

- **same_scale** – A boolean value indicates whether to use a same scale factor to resize all images in `image_list`. Set it to be `True` if you want to visualize the sizes of different images.

Returns

Pasted `Image.Image` instance.

`svkcore.visualize.visualize.pil2cv2image(image: Image) → ndarray`

Convert `PIL.Image.Image` to openCV format image

Parameters

image – an instance of `PIL.Image.Image`

Returns

converted openCV format image

CHANGE LOGS

3.1 2023/03/10

- add new feature to `image_gallery`: resize all image by same scale
- add `setup.py` to install package
- add docs

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